

Welcome to CANbedded

Software Components for
Communication and Diagnostics.

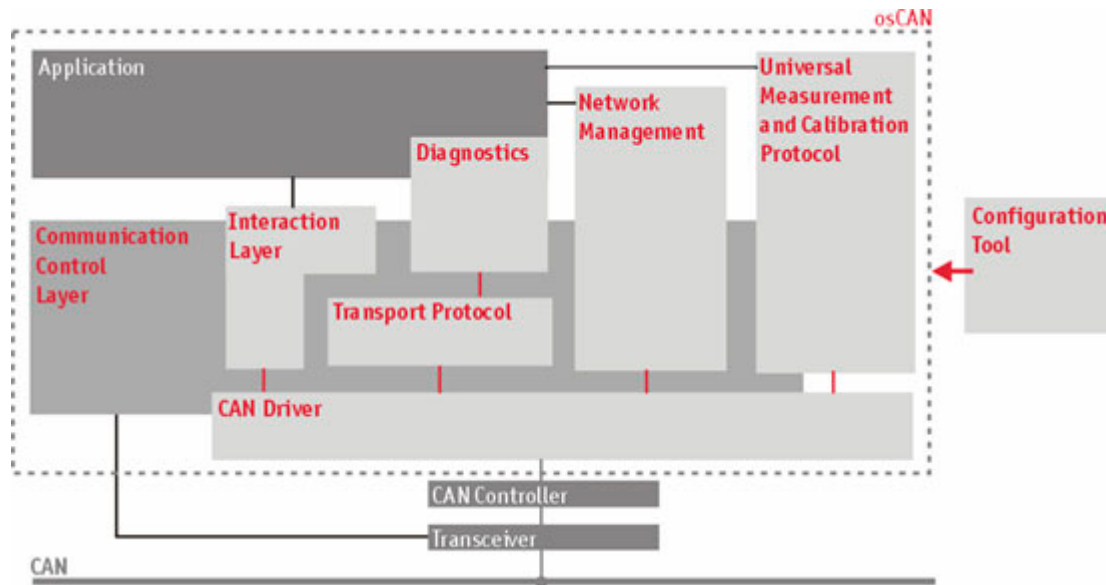
Get To Know The CANbedded Environment

The picture shows the layer model of the CANbedded components, their basic functions and connections.

CANbedded consists of a set of **source code components** you have to **include in your application**. The sort of components depends on your **delivery**.

The **Configuration Tool** is the **connection** between the components and your project specific needs. It generates files you also have to include in your application.

CANbedded Software Components



Configuration Tool

for parameters and configuration of all components

more see Online Help

Communication Control Layer

software component integration and hardware abstraction.

CAN Driver

hardware specific CAN chip characteristics and provision of a standardized application interface

Interaction Layer

with signal interface

Network Management

to control the CAN bus

Transport Protocol

for data exchange of more than 8 data bytes

Universal Measurement and Calibration Protocol

measurement and calibration of the ECU via different bus systems.

Diagnostics Layer

according to Keyword Protocol 2000 / UDS

[How to start with ...](#) [slide 3](#)

[CANbedded tutorials](#) [slide 4](#)



How to start with CANbedded Software Components



Follow the install shield wizard to unpack your delivery



Open the Configuration Tool (CANgen, DBKOMgen, GENy)

Create a new configuration, insert compiler, derivative, data base file and select your node

Configure all CANbedded Components that you want to use



Generated the files

Add the generated files to your application project

Adapt you application to CANbedded Software Components

- ☐ Includes
- ☐ Initialization
- ☐ cyclic calls
- ☐ callback functions ...

Compile and link the project

Download and Test

[CANbedded environment](#) [slide 2](#)
[CANbedded tutorials](#) [slide 4](#)

Get To Know The CANbedded Tutorials

- ❑ Beginners of CANbedded components should read the **UserManual_Startup_<OEM>_CANbedded** first.
- ❑ If not part of the delivery read the component specific user manuals **UserManual_<Component>**. And if you use the CCL read the CCL user manual first.
- ❑ There is a set of **user manuals** and **references** for every component as you see below.

Document Types

UserManual

FIRST steps to get an example executable running for each **component** or the **complete delivery** (if available for you OEM).

e.g. **UserManual_CCL**, **UserManual_Startup_<OEM>_CANbedded**

Technical Reference(SW)

More detailed information about the component, API... e.g.

TechnicalReference_candrv

Technical Reference(HW)

Hardware specific information of the component if available.

e.g. **TechnicalReference_CAN_HC12**

CANbedded environment slide 2

How to start with ... slide 3

